Wave attenuation behind a reef

Cedric Monteiro ISITV, France Kim Klaka CMST, Australia To determine whether an anchorage is comfortable, need to predict:

- Environment wind, waves, current
- vessel orientation to waves
- resulting vessel motions

Project aims

- Develop a model of wave attenuation over a reef
- validate said model by full scale experiment

Monochromatic model

$$\frac{d(EC_g\cos\theta)}{dx} = \frac{\kappa}{h} \Big[EC_g - EC_{g_s} \Big] + \frac{\rho C_f}{6\pi} \Big(\frac{2\pi H}{T\sinh kh} \Big)^3$$

- E is the wave energy per unit surface area of ocean:
- κ is an empirical decay coefficient (=0.15).
- *h* is the water depth.
- EC_{gs} is the energy flux associated with stable wave height H_s= Γ h, where Γ =0.4.
- H is the wave height
- *T* is the wave period
- θ is the incident wave direction
- ρ is the sea water density
- *x* is the wave direction propagation
- *k* is the wave number
- C_f is the bottom friction coefficient.
- *C* the phase velocity

Comparison with lab expt



Spectral model

 $\frac{\partial EC_g}{\partial x} + D = 0$

 $D = \frac{\alpha}{4} Q_b f_p \rho g H_b^2$ $Q_b = P(h > H_b) = \exp(-\frac{H_b^2}{m_0})$

Field experiment 16/6/00

- Longreach Bay, Rottnest
- CMST seabed and floating sensors
- deploy inside and outside reef
- measure water depth over reef







results



More results



Conclusions

- Model works well
- water depth over reef is critical
- research in waves can be wet!